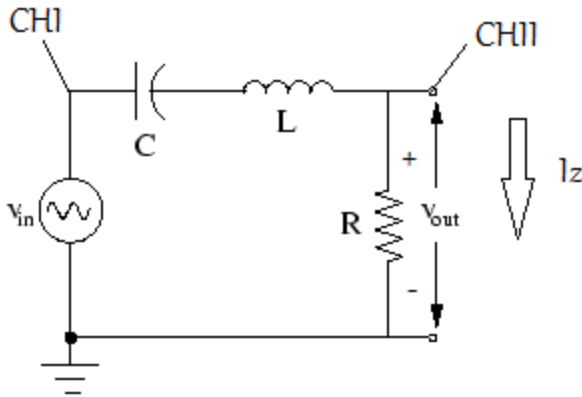


Ece 232 - Advanced Electrical Circuit Analysis Lab Manual 4



$$L = 0.1 \text{ H}, C = 10 \mu\text{F}, R = 1 \text{ k}\Omega$$

$$V_{in}(t) = 1 \sin 2\pi ft$$

$$f = 2500 \text{ Hz}$$

CHI → The voltage observed over the Z (V_Z) where $Z = sL + \frac{1}{sC} + R$

[Since all components are in series]

CHII → $V_{out} = RI_Z \rightarrow I_Z$ (in mA) [I_Z is the total current over the impedance Z]

- ✓ V_Z is shown by CHI in Volts.
- ✓ I_Z is shown by CHII in mAmps.

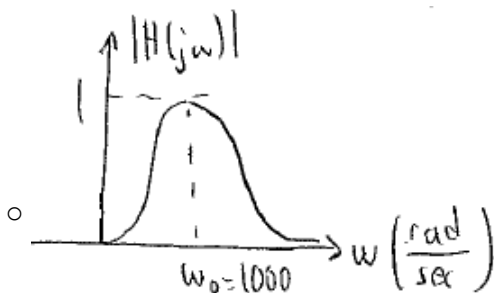
Hence the CHI vs. CHII will show the voltage/current relation for Z.

$$|H(j\omega)| = \frac{1000j\omega}{\sqrt{(10^5 - 0.1\omega^2)^2 + (1000\omega)^2}}$$

$$H(j\omega) = \frac{V_{out}(j\omega)}{V_{in}(j\omega)} = \frac{1000j\omega}{(10^5 - 0.1\omega^2) + (1000j\omega)}$$

- ✓ Resonant frequency equate real part of the denominator of $H(j\omega)$ to 0.

Hence $10^5 - 0.1\omega^2 = 0 \rightarrow \omega_0 = 1000 \text{ rad/sec}$ {resonant freq.}



- If $f=2500\text{Hz}$ and $w=15700\text{rad/sec}$

$$H(jw) = \frac{1000jw}{(10^5 - 0.1w^2) + (1000jw)}$$

$$\angle H(jw) = \angle V_{out}(jw) - \angle V_{in}(jw) = 90 - \tan^{-1} \frac{1000w}{(10^5 - 0.1w^2)}$$

$$w = 0 \rightarrow \angle H(jw) = 90$$

$$w = w_0 = 1000\text{rad/sec} \rightarrow \angle H(jw) = 0$$

$$w = 15700\text{rad/sec} \rightarrow 90 - \tan^{-1} \frac{1000w}{(10^5 - 0.1*(15700)^2)} = 90 - \tan^{-1} \frac{157}{-245.49}$$

$$\angle H(jw) = 90 - 148 = -58$$

$$\angle H(jw) = \angle V_{out}(jw) - \angle V_{in}(jw) = \angle I_Z - \angle V_Z = -58$$

$V_{in}(V_Z)$ is leading $V_{out}(I_Z)$ by 58° . \rightarrow The impedance is inductive.

$$T = \frac{1}{f} = \frac{1}{2500\text{Hz}} = 0.4\text{msec}$$

d : phase distance

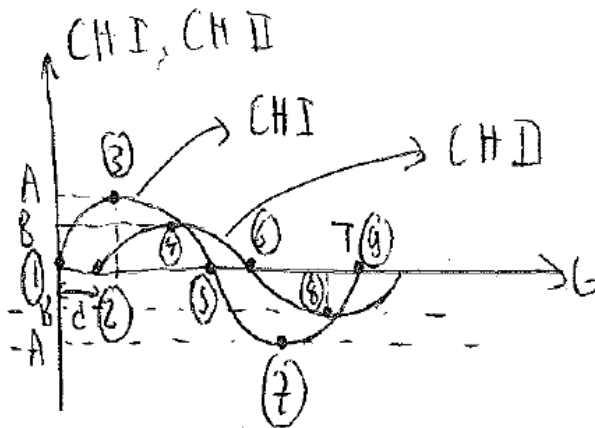
$$\theta: \text{phase difference} = \frac{d}{T} * 360$$

$$\angle H(jw) = -\angle Z(jw) = -58$$

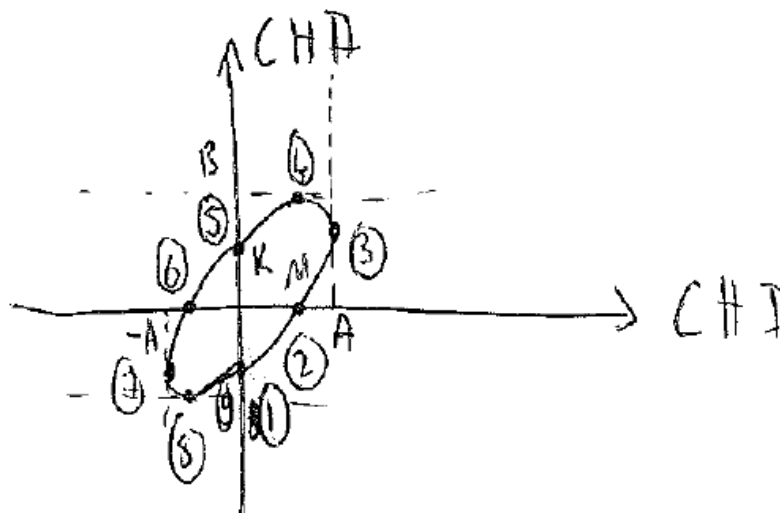
$$\angle Z(jw) = 58 \{V_Z \text{ is leading } I_Z, I_Z \text{ is lagging } V_Z\}$$

$$|\angle Z(jw)| = \frac{A}{B} \quad \text{when } w = 15700\text{rad/sec}$$

- ❖ Y-T mode [CHI and CHII are drawn w.r.t time t]



- ❖ Corresponding X-Y mode



$$|\angle Z(j\omega)| = \frac{A}{B}$$

$$\angle Z(j\omega) = \arcsin \frac{K}{B} = \arcsin \frac{M}{A}$$

Although we can find the phase by $\angle Z(j\omega) = \arcsin \frac{K}{B} = \arcsin \frac{M}{A}$ we cannot identify precisely whether the phase is lagging or leading (we cannot say CHI is leading or lagging)