

Q-1

$$H(j\omega) = \frac{2}{1 + 10^{-2}(j\omega)^2 + 10^{-1}j\omega} = \frac{2}{(1 - 10^{-2}\omega^2) + 10^{-1}j\omega}$$

(a)  $|H(j\omega)| = \frac{2}{\sqrt{\left(1 - \frac{\omega^2}{100}\right)^2 + \left(\frac{\omega}{10}\right)^2}}$

$|H(j\omega)| \Big|_{\omega=0} = 2$        $\lim_{\omega \rightarrow \infty} |H(j\omega)| = 0$        $|H(j\omega)| \Big|_{\omega=10} = 2$

$$\frac{d|H(j\omega)|}{d\omega} = 2 \left[ \frac{0 - 1 + \left[ 2 \left(1 - \frac{\omega^2}{100}\right) \left(\frac{-2\omega}{100}\right) + 2 \left(\frac{\omega}{10}\right) \frac{1}{10} \right]}{\left(1 - \frac{\omega^2}{100}\right)^2 + \left(\frac{\omega}{10}\right)^2} \right]^{-1/2}$$

$$= -2 \frac{2 \left(1 - \frac{\omega^2}{100}\right) \left(\frac{-2\omega}{100}\right) + 2 \left(\frac{\omega}{10}\right) \frac{1}{10}}{\left[ \left(1 - \frac{\omega^2}{100}\right)^2 + \left(\frac{\omega}{10}\right)^2 \right]^{3/2}}$$

$$= -2 \frac{\frac{1}{50} \left[ \left(1 - \frac{\omega^2}{100}\right) (-2\omega) + \omega \right]}{\left[ \left(1 - \frac{\omega^2}{100}\right)^2 + \left(\frac{\omega}{10}\right)^2 \right]^{3/2}} = -2 \frac{\frac{1}{50} \left[ \omega \left(-2 + \frac{\omega^2}{50} + \omega\right) \right]}{\left[ \left(1 - \frac{\omega^2}{100}\right)^2 + \left(\frac{\omega}{10}\right)^2 \right]^{3/2}}$$

if  $\frac{d|H(j\omega)|}{d\omega} = 0 \Rightarrow \omega = 0$  or  $\left(2 + \frac{\omega^2}{50} + \omega\right) = 0 \Rightarrow \omega^2 + 50\omega - 100 = 0$

$$\omega = \frac{-50 \pm \sqrt{2500 + 400}}{2}$$

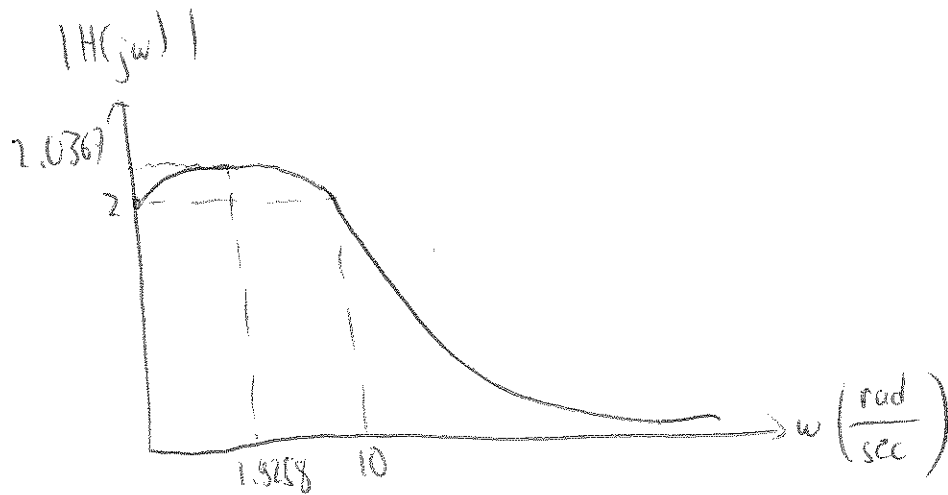
$\omega_1 = 5\sqrt{29} - 25$   
 $\omega_2 = 5\sqrt{29} + 25$

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Q-1 (continue)

when  $\omega = 5\sqrt{29} - 25 = 1.92582$   $|H(j\omega)|$  is maximized

$$\frac{|H(j\omega)|}{\omega = 5\sqrt{29} - 25} = 2.0367$$

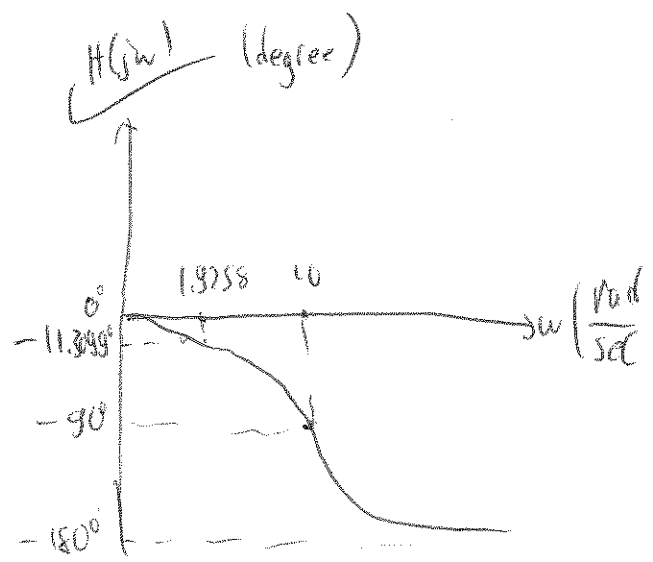


(b)  $\angle H(j\omega) = \tan^{-1} \frac{\omega}{10} - \frac{N(\omega)}{D(\omega)}$   $\angle H(j\omega) \Big|_{\omega=0} = \tan^{-1} \frac{0}{1} = 0^\circ$

$\lim_{\omega \rightarrow \infty} \angle H(j\omega) = \tan^{-1} \frac{\infty}{-\infty}$  however  $\deg N(\omega) = 1 < \deg D(\omega) = 2$   
 $= -180^\circ$

$\lim_{\omega \rightarrow 10^-} \angle H(j\omega) = -90^\circ$   $\lim_{\omega \rightarrow 10^+} \angle H(j\omega) = -90^\circ$

$\lim_{\omega \rightarrow 5\sqrt{29} - 25} \angle H(j\omega) = -11.3099^\circ$



Q-2-

$$|H(j\omega)| = \frac{100 - \omega^2}{\sqrt{(100 - \omega^2)^2 + (15\omega)^2}} = \frac{|100 - \omega^2|}{\sqrt{\omega^4 + 25\omega^2 + 10^4}} = \frac{100 - \omega^2}{D(\omega)}$$

(a)

$$|H(j\omega)| = 1 \quad \omega = 0$$

$$|H(j\omega)| = 0 \quad \omega = 10$$

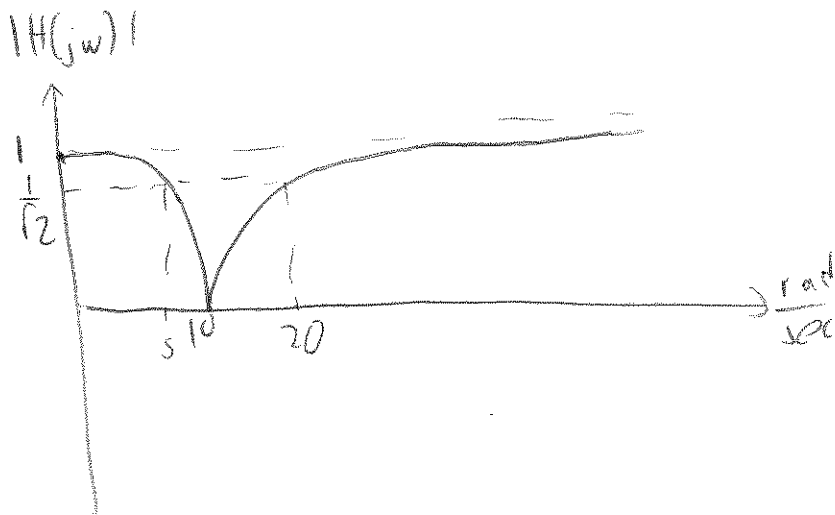
$$\lim_{\omega \rightarrow \infty} |H(j\omega)| = 1$$

$$\frac{d|H(j\omega)|}{d\omega} =$$

$$\left\{ \begin{array}{l} \frac{2\omega D(\omega) - \frac{dD(\omega)}{d\omega} (100 - \omega^2)}{D^2(\omega)} \rightarrow \text{positive} \quad 0 < \omega < 10 \\ \frac{2\omega D(\omega) + \frac{dD(\omega)}{d\omega} (\omega^2 - 100)}{D^2(\omega)} \rightarrow \text{positive} \quad 10 < \omega \end{array} \right.$$

~~monotonically~~

$|H(j\omega)| \rightarrow$  decreasing when  $0 < \omega < 10$   
 $|H(j\omega)| \rightarrow$  increasing when  $10 < \omega$



if  $\omega = 5$

$$|H(j\omega)| = \frac{1}{\sqrt{2}}$$

if  $\omega = 20$

$$|H(j\omega)| = \frac{1}{\sqrt{2}}$$

(Q-2) continue

(b)  $\angle H(j\omega) = \begin{cases} 0^\circ - \tan^{-1} \frac{15\omega}{100-\omega^2} & 0 < \omega < 10 \\ 180^\circ - \tan^{-1} \frac{15\omega}{100-\omega^2} & 10 < \omega \end{cases}$

$\lim_{\omega \rightarrow 10^-} \angle H(j\omega) = -90^\circ$        $\lim_{\omega \rightarrow 10^+} \angle H(j\omega) = 90^\circ$

if  $\frac{15\omega}{100-\omega^2} = 1$        $15\omega = 100 - \omega^2$        $\omega^2 + 15\omega - 100 = 0$

$\omega_{1,2} = \frac{-15 \pm \sqrt{225 + 400}}{2}$

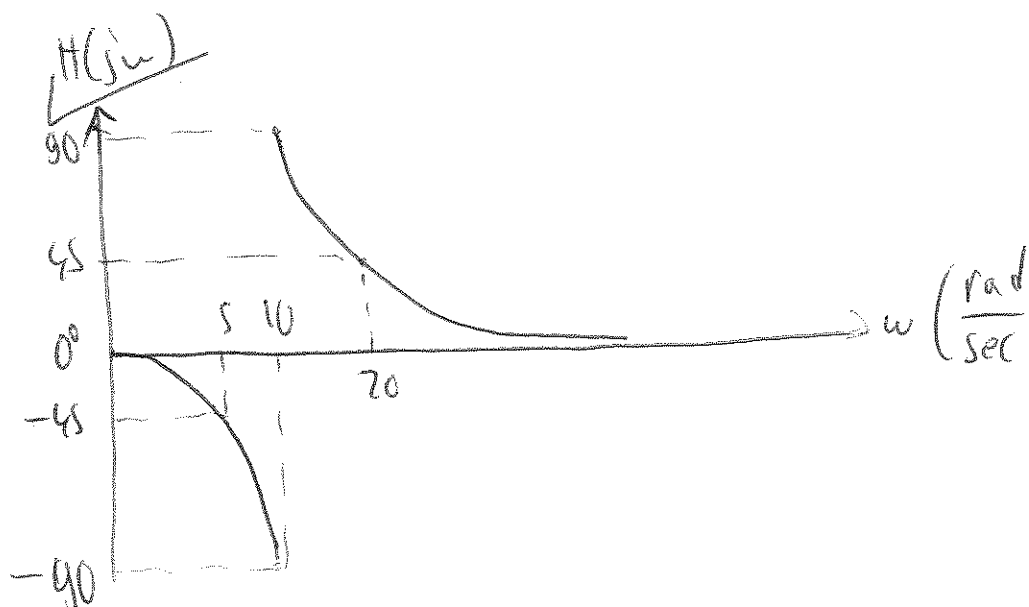
$= \frac{-15 \pm 25}{2} = -20, 5 \frac{\text{rad}}{\text{sec}}$

if  $\omega = 5$        $\angle H(j\omega) = 0 - \tan^{-1} \frac{1}{1} = -45^\circ$

if  $\frac{15\omega}{100-\omega^2} = -1$        $15\omega = -100 + \omega^2$        $\omega^2 - 15\omega - 100 = 0$

$\omega_{1,2} = \frac{15 \pm \sqrt{225 + 400}}{2} = 20, -5 \frac{\text{rad}}{\text{sec}}$

if  $\omega = 20$        $\angle H(j\omega) = 180 - \tan^{-1} \frac{300}{-300} = 180 - 135 = 45^\circ$



Q-3

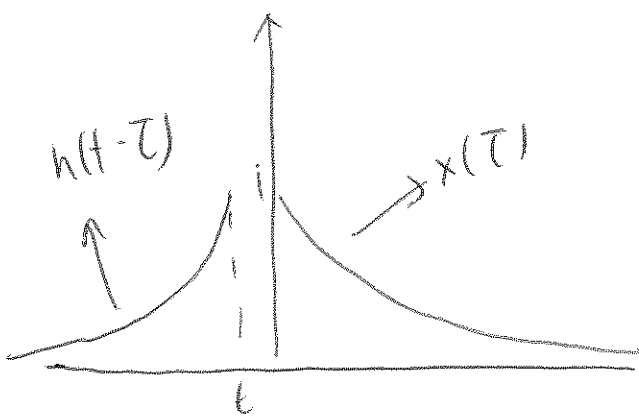
$$h(t) = e^{-t} u(t) \quad x(t) = e^{-t} u(t)$$

$$y(t) = \int_{-\infty}^t x(\tau) h(t-\tau) d\tau$$

if  $t < 0$

$$x(\tau) = e^{-\tau} u(\tau), h(t-\tau) = e^{-(t-\tau)} u(t-\tau)$$

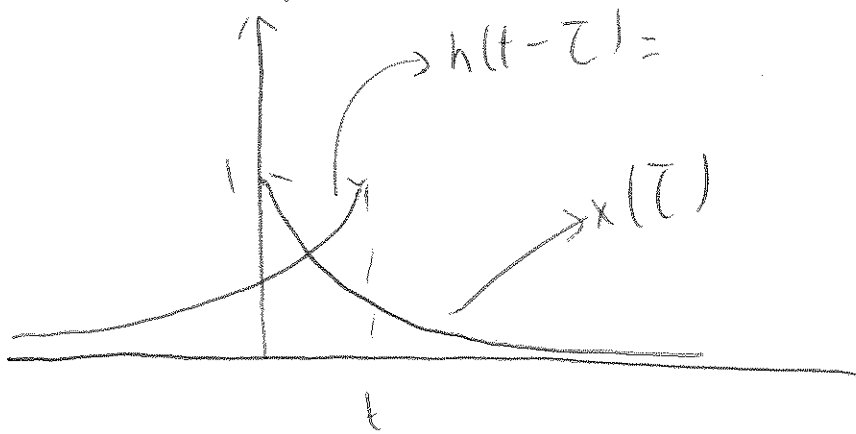
$x(\tau), h(t-\tau)$



$$y(t) = \int_{-\infty}^t x(\tau) h(t-\tau) d\tau = 0$$

if  $t > 0$

$x(\tau), h(t-\tau)$



$$y(t) = \int_{-\infty}^t x(\tau) h(t-\tau) d\tau = \int_{-\infty}^0 0 + \int_0^t e^{-\tau} u(\tau) e^{-(t-\tau)} u(t-\tau) d\tau$$

$$= \int_0^t e^{-t-\tau} e^{\tau} d\tau = e^{-t} \int_0^t 1 d\tau$$

$$= e^{-t} \tau \Big|_0^t$$

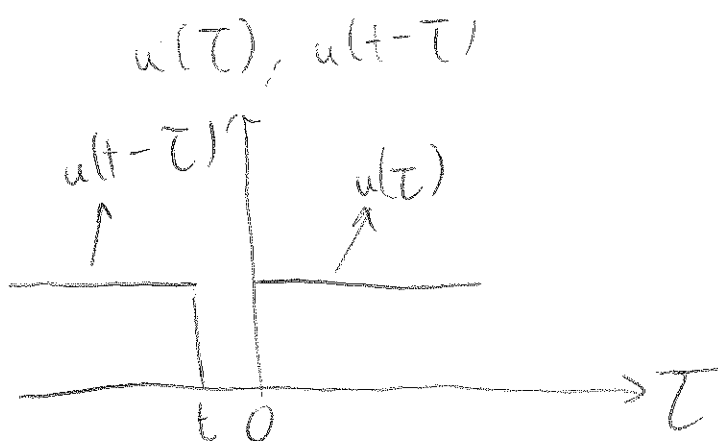
$$= t e^{-t}$$

Q-3 continue

hence  $y(t) = \begin{cases} 0 & t < 0 \\ te^{-t} & t > 0 \end{cases}$

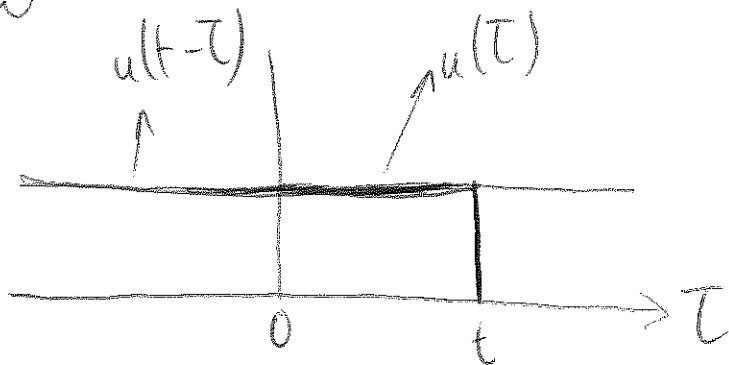
Q-4-  $y(t) = \int_{-\infty}^t a(\tau) u(t-\tau) d\tau$

$t < 0$



$$y(t) = \int_{-\infty}^t a(\tau) u(t-\tau) d\tau = 0 //$$

$t > 0$



$$y(t) = \int_{-\infty}^t a(\tau) u(t-\tau) d\tau = \int_{-\infty}^0 0 d\tau + \int_0^t \underbrace{a(\tau)}_1 \underbrace{u(t-\tau)}_1 d\tau = \int_0^t 1 d\tau = \tau \Big|_0^t = t //$$

$$y(t) = \begin{cases} 0 & t < 0 \\ t & t > 0 \end{cases} = r(t) = \text{ramp function} //$$